Estimating the width of uniform distribution under measurement errors

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Convolution model

- $X = U + \varepsilon$
- *U* i ε independent, random
- U uniform, ε normal error
 Example: U ~ U(-a, a), ε ~ N(0, σ²)

$$f_X(x; a, \sigma) = \frac{1}{2a} \left(F_{\varepsilon} \left(\frac{x+a}{\sigma} \right) - F_{\varepsilon} \left(\frac{x-a}{\sigma} \right) \right)$$



- Usually assumed that ε is normally distributed.
- Known as the Flatten-Gaussian distribution
- The basis for calculating the measurement uncertainty
 - Blázquez, J., García-Berrocal, A., Montalvo, C., Balbás, M. (2008). The coverage factor in a Flatten–Gaussian distribution, Metrologia 45, 503–506.
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- Ex. for estimating the age of stage boundaries.

 For modeling the transmission losses data Tolić, I., K. Miličević, N. Šuvak, I. Biondić (2017). Non-linear Least Squares and Maximum Likelihood Estimation of Probability Density Function of Cross-Border Transmission Losses, IEEE Transactions on Power Systems 33/2 (2018), 2230–2238

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Black fungi colonies



Garlipp, T., Müller, C. H., Detection of linear and circular shapes in image analysis, Computational Statistics & Data Analysis 51 (2006), 1479–1490



https://cran.r-project.org/web/packages/LeArEst/

- M. Benšić, P. Taler, S. Hamedović, E.K. Nyarko, K. Sabo, *LeArEst:* Length and Area Estimation from Data Measured with Additive Error, The R Journal 9/2 (2017), 461-473
- Includes web application for estimating the size of an object from a noisy image
- Gaussian error model tested in simulations

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Image of the can, r = 51.5mm, area = $8332.3mm^2$



- Hough transformation
 - P. V. Hough, Method and means for recognizing complex patterns.
 Patent U.S. Patent No. 3,069,654, 1962.
 R. D. Duda i P. E. Hart, Use of the Hough transform to detectlines and curves in pictures, Commun. ACM, 15, br. 1, 1972.
 A. Rosenfeld, Picture processing by computer, ACM Computing Surveys (CSUR), svez. 1, br. 3, pp. 147-176, 1969.
- EDCirlces

C. Akinlar i C. Topal, *EDCircles: A real-time circle detector with a false detection control*, Pattern Recognition, 46, br. 3, pp. 725-740, 2013.

Fornaciari

M. Fornaciari, A. Prati i R. Cucchiara, *A fast and effective ellipse detector for embedded vision applications*, Pattern Recognition, 47, br. 11, pp. 3693-3708, 2017.

- r = 51.5mm, area = $8332.3mm^2$
- 20 simulations for each sd
- RMSE for area estimation

sd/r(%)	LeArEst	Hough	EDCircles	Fornaciari
0	229	1858	681	
5	587	1353	723	
13	523	1365	852	
26	243	2315	659	
39	289	1955	755	

• For 1000 simulations we have similar results but withouth EDCircles.

Problem with real images



Laplace error model — improvement



- $X = U + \sigma \varepsilon$
- $f_U(t) = \frac{1}{2a} I_{[-a,a]}(t)$
- ε absolutely continuous random variable with distribution F_{ε} and density function f_{ε} , which is even.

٠ $\Rightarrow f_X(t) = \frac{1}{22} [F_{\varepsilon}(\frac{a+t}{\sigma}) - F_{\varepsilon}(\frac{a-t}{\sigma})]$ • $\varepsilon \sim \mathcal{N}(0,1)$ $f_X(t|a,\sigma) = \frac{1}{2a\sqrt{2\pi}} \int_{\frac{a+t}{\sigma}}^{\frac{a-t}{\sigma}} e^{-\frac{u^2}{2}} du$ • $\varepsilon \sim \mathcal{L}(\lambda), \ \sigma = 1$ $f_X(t|a,\lambda) = \begin{cases} \frac{1}{2a} \sinh \frac{a}{\lambda} e^{-\frac{|t|}{\lambda}}, & a \in (0,|t|], \\ \frac{1}{2a} \left(1 - e^{-\frac{a}{\lambda}} \cosh \frac{t}{\lambda}\right), & a \in (|t|,\infty). \end{cases}$

General one-dimensional model - density



red — normal error blue — Student's t(1) error • Data (x₁,...,x_n), log-likelihood:

$$I(a) = -n\log 2a + \log \sum_{i=1}^{n} \left[F_{\varepsilon} \left(\frac{x_i + a}{\sigma} \right) - F_{\varepsilon} \left(\frac{x_i - a}{\sigma} \right) \right]$$

- Differentiable function (model with absolutely continuous error).
- Optimization should be easy with a good initial approximation that is not difficult to recognize in applications.
- Regularity conditions???

- Easy to check sufficient conditions
- S. Hamedović, MB, K. Sabo, *Estimating the width of a uniform distribution under symmetric measurement errors*, submitted 2019
- Examples: Normal, Logistic, Student's $t(
 u), \nu \geq 1$
- Student's distribution with small degrees of freedom could be a particularly good choice for the error. (We can adjust the number of degrees of freedom to the amount of outliers in the data.)

ML confidence intervals

Fisher information

$$I(a) = \frac{-1}{a^2} + \frac{1}{2a\sigma^2} \int_{-\infty}^{\infty} \frac{\left(f_{\varepsilon}\left(\frac{x+a}{\sigma}\right) + f_{\varepsilon}\left(\frac{x-a}{\sigma}\right)\right)^2}{F_{\varepsilon}\left(\frac{x+a}{\sigma}\right) - F_{\varepsilon}\left(\frac{x-a}{\sigma}\right)} \, dx$$
$$\left(\hat{a}_{ML} - \frac{z_{1-\alpha/2}}{\sqrt{nI(\hat{a}_{ML})}}, \hat{a}_{ML} + \frac{z_{1-\alpha/2}}{\sqrt{nI(\hat{a}_{ML})}}\right)$$

LR test

$$H_0$$
: $a = a_0$
 H_1 : $a \neq a_0$

Critical region (significance level α , *L* likelihood)

$$\left\{ \mathbf{y} | -2\log \frac{L(a_0; \mathbf{y})}{L(\hat{a}_{ML}; \mathbf{y})} \ge \chi_1^2 (1 - \alpha) \right\}$$

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M. Benšić, K. Sabo, S. Hamedović

Uniform distribution under measurement error



Blood artery



Blood artery



Blood artery

